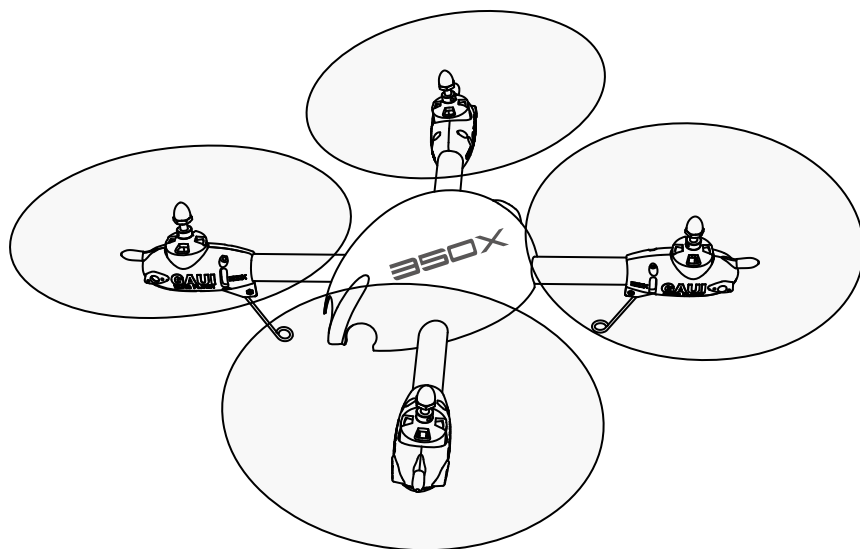
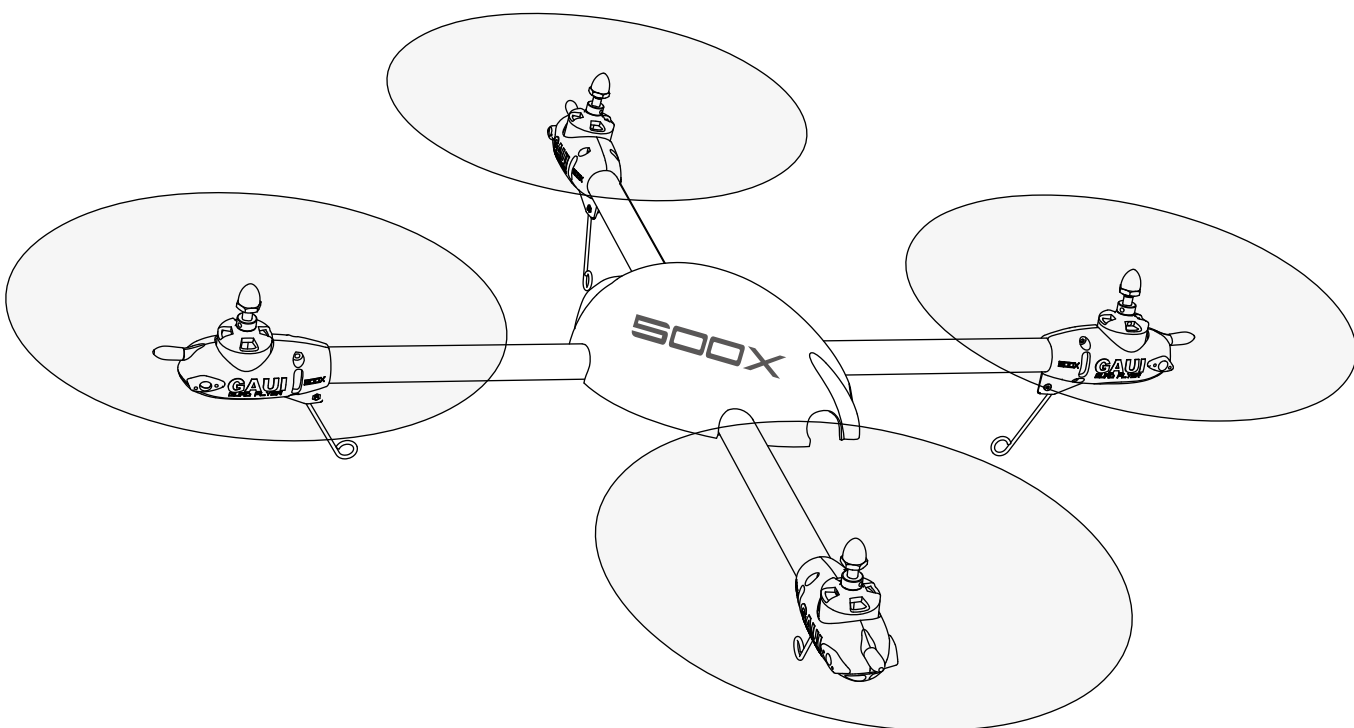




MULTI•ROTOR TECHNOLOGY V1.0



QUAD FLYER



We recommend downloading and using the latest manual from Official **MRT** website's download area.

我們建議您從 **MRT** 官方網站的下載區下載，並使用最新的手冊。

www.gauimrt.com


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Thank you for purchasing MRT Multi-Rotor from Tai Shih Hobby Corporation (TSH). We hope you will enjoy the joy of flight. In order to understand full assembly sequences, this instruction manual show the assembly information of this model, even though some elements might be supplied as pre-assembled. Please refer to manual whenever carrying out maintenance or replacing parts.

感謝您購買泰世科技出品的 **MRT** 多旋翼飛行器，我們希望您可以盡情享受飛行的樂趣。為了要讓使用者詳細瞭解組裝順序，即使有些部件已經預先組裝完成，本說明書將提供這台遙控模型的組裝資訊。同時，敬請參閱保養與主要零件更換資訊。

CAUTION: This radio controlled Multi-Rotor is not a toy.

警告：這台遙控多旋翼飛行器不是玩具。

SAFETY PRECAUTIONS

This kit includes some pre-assembled components. Please check for any loose screws and tighten them before you proceed with assembly.

You are responsible for assembly, safe operation, maintenance, inspection and adjustment of the model.

Before beginning assembly, please read these instructions thoroughly.

Check all parts. If you find any defective or missing parts, contact your local dealer or TSH distributor.

Before you proceed to Multi-Rotor activity, please check and follow thoroughly related regulation of aero modeling in your country/region.

安全資訊與注意事項

這台遙控模型包含預先組合完成的部件。

在進行組裝之前，請仔細檢查這些預先組裝部件上的所有螺絲均有仔細鎖緊。

您有完全的責任對於這台遙控模型的組裝，安全操作，保養，檢查與調整。

請先檢查所有的零件，如果發現任何不良品，遺失品，請向購買的模型店或是當地的泰世代理商連絡。在您進行遙控多旋翼活動時，請先詳細瞭解與遵守當地遙控模型的相關法規。

Disclaimer

This product is for a radio controlled (RC) Multi-Rotor.

Improper operation, maintenance or assembly can potentially cause a RC Multi-Rotor to pose a danger to persons or objects including but not limited to the possibility of causing serious physical injury and even death.

Moving components can present a hazard to operators, and anyone or anything that could be in the flying area of the RC Multi-Rotor.

Under no circumstance should a minor be allowed to operate this RC Multi-Rotor without the approval, monitor and direction of his parent or legal guardian who takes full responsibility for all of the minor's actions.

This product is intended for being operated by experienced mature RC Multi-Rotor pilots under controlled safety conditions and on locations properly authorized and setup for safe flying and away from other people.

Do not operate an RC Multi-Rotor within the vicinity of residences, trees, electrical power lines during inclement weather or near crowds of people.

The manufacturer and/or its distributors assume no responsibility or liability whatsoever for any damages including but not limited to ones generated by incidental or consequential damages.

The operator of the Multi-Rotor assumes all responsibility and liability that result from the correct or incorrect operation of the Multi-Rotor.

免責聲明

本產品是無線遙控的多旋翼飛行器。

不當的操作，保養或是組裝有可能導致遙控多旋翼飛行器對於人身或是物品造成危險。

包括，但是不局限於對於人體產生嚴重傷害甚至死亡的可能性。

所有的移動部件可能對於操作的使用者，旁人或是這台遙控多旋翼飛行場的任何人或物品產生傷害。

未成年的人如果要操作這台遙控多旋翼飛行器需要父母或是監護人的同意，並在監督與指導下才能進行操作並遠離周遭障礙物及人群等，其父母或是監護人需負起所有責任與法律責任。

以下場合與情況禁止操作遙控多旋翼飛行器：居家房屋附近、天候不佳時、非空曠區域、樹木、電線竿或是人群附近。

製造廠商與其經銷商都不對於所有的傷害，包含但是不局限於偶然或是連續發生的傷害負擔任何責任。

本產品的使用者要對於正確地或是不正確地操作的結果需負擔所有責任。

本產品一但離開製造廠商的控制範圍外，製造廠商無法對於下列事項保持監督與控管：組裝，保養，維修與操作這台遙控多旋翼飛行器。

The Academy of Model Aeronautics (AMA) is a national organization representing modelers in the United States.

Please refer to the National Model Aircraft safety code from AMA Member Manual for details: <http://www.modelaircraft.org/files/mmanual.pdf>

These special codes and appropriate documents may be obtained either from the AMA Web site at www.modelaircraft.org or by contacting AMA.

Academy of Model Aeronautics

5161 East Memorial Drive

Muncie, IN 47302

Tel.: (765) 287-1256

Fax: (765) 289-4248

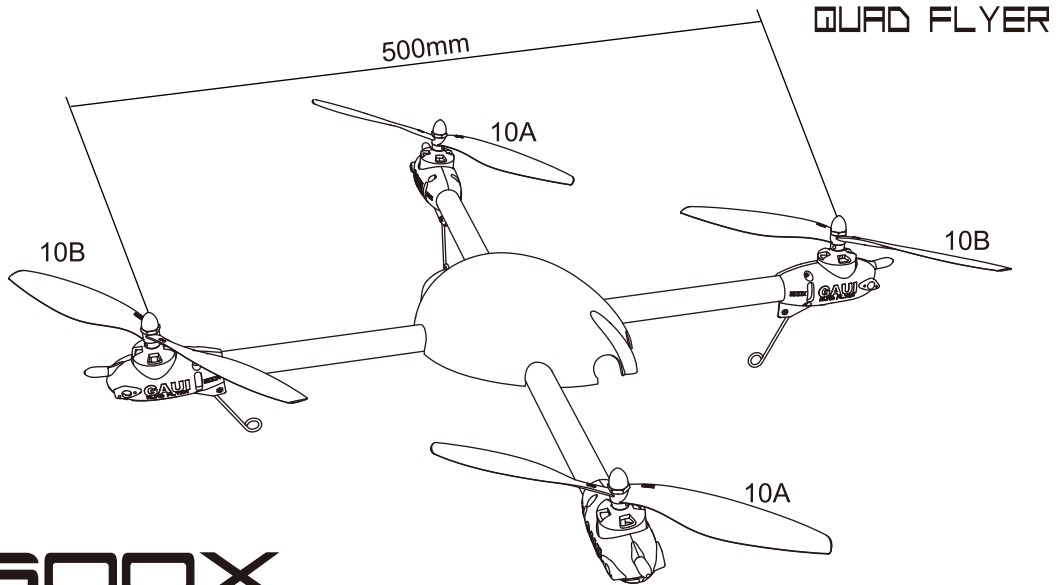
Usage Cautions

When flying, the fast rotating propellers of Multi-Rotor can cause serious damage and injury.

Therefore, please fly with a high safety consciousness, keep multi-rotor away from human beings, power lines, obstacles and properties etc....

1. Do not get close to or even touch the working motors and propellers, which can cause serious injury.
2. Check all propellers and motors are installed correctly and secured firmly before each flight.
3. Do not fly with old or broken parts. Check all parts of the multi-rotor are in good condition before each flight.
4. Make sure the rotation direction of each propeller is correct (CW or CCW).
5. Do not overload the multi-rotor.

If you have any problem you cannot solve during installation, please contact your local distributor for timely customer service.

**QUAD FLYER**

500X

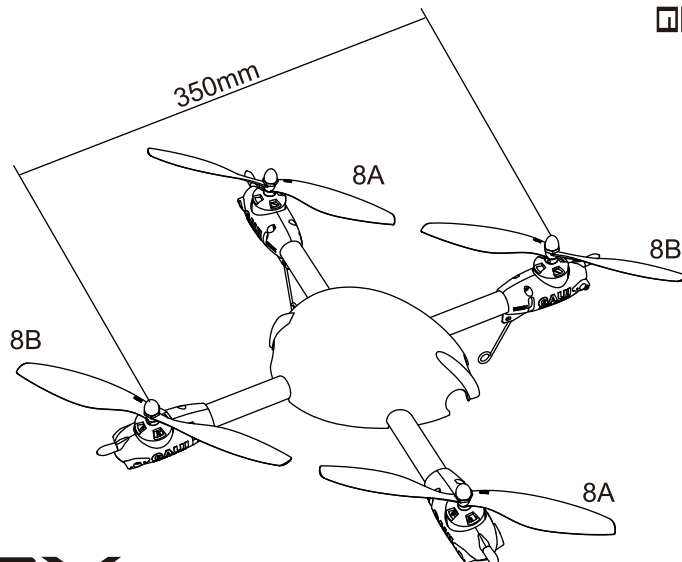
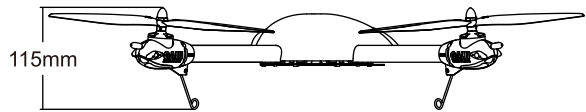
Max flying weight : 2000g

10 inch prop.

Weight : 650g (without battery).

Battery : 2S ~3S LiPo

4~5CH radio control system

**QUAD FLYER**

350X

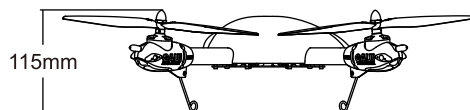
Max flying weight : 1100g

8 inch prop.

Weight : 630g (without battery).

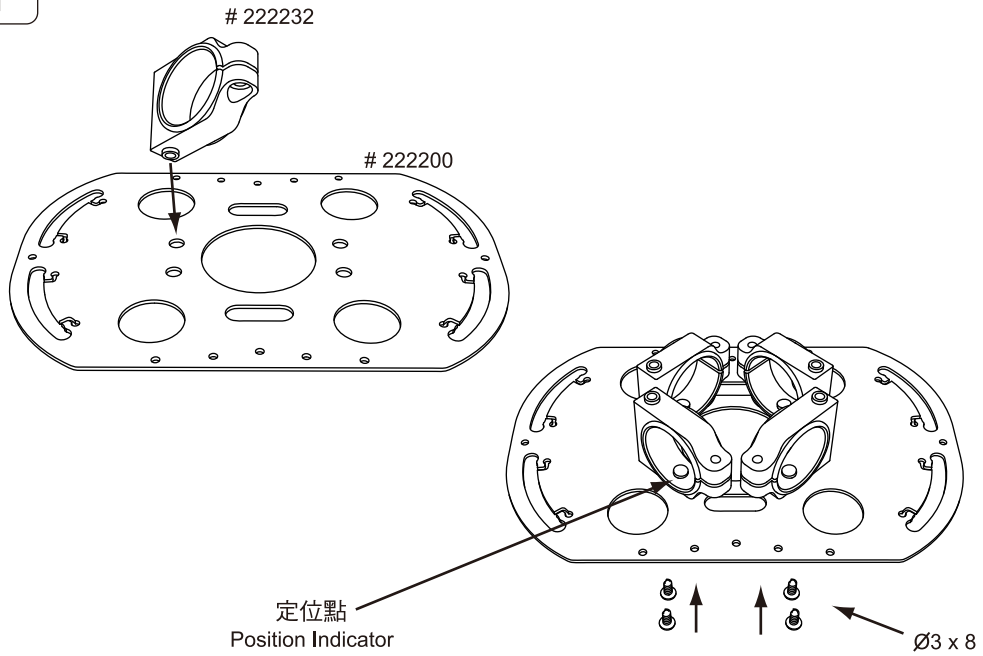
Battery : 2S ~3S LiPo

4~5CH radio control system



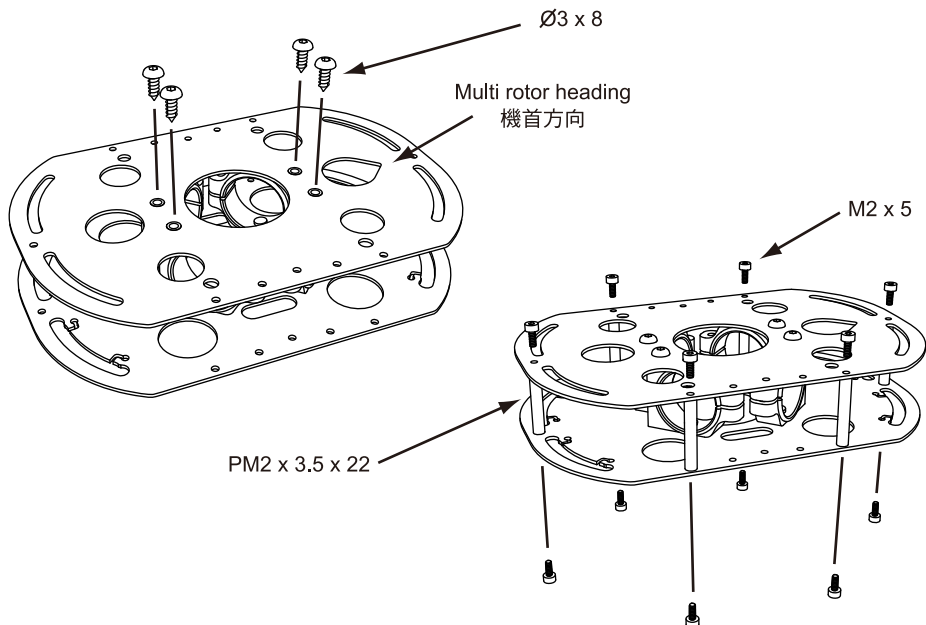
Start with Bottom side of Main Frame. Insert pivot point of Inside Boom Holder into pivot hole and lock in place with screw (Ø3 x 8). (Attention: Position Indicator is on bottom).
將內部套環凸點鑲入孔內並鎖緊。(注意：定位點在下方)

1



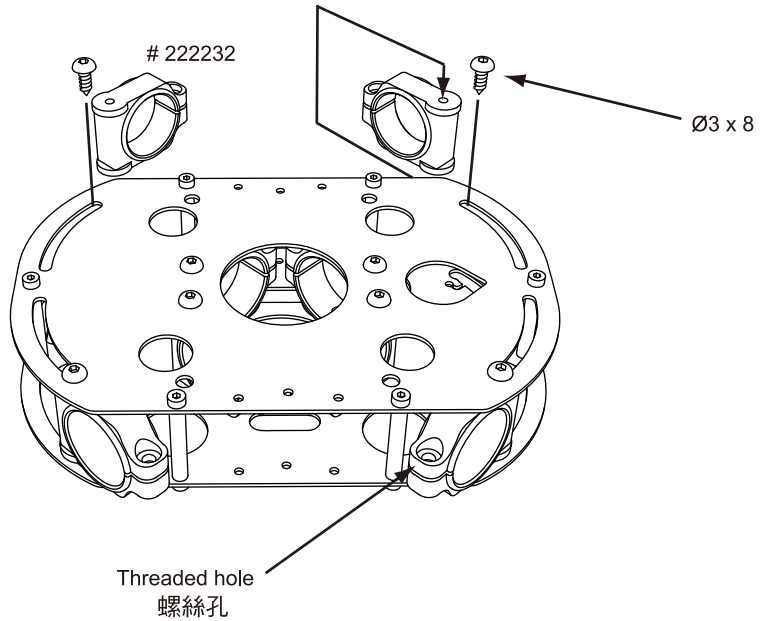
Put on Top of Main Frame. Insert the 4 pivot points into the 4 pivot hole on Top Main Frame and lock in place with screws (Ø3 x 8). Insert the 6 aluminum posts (PM2 x 3.5 x 22) and lock in place with screws (M2 x 5).
上方也同樣鎖緊，並將六支鋁柱固定至機身。

1



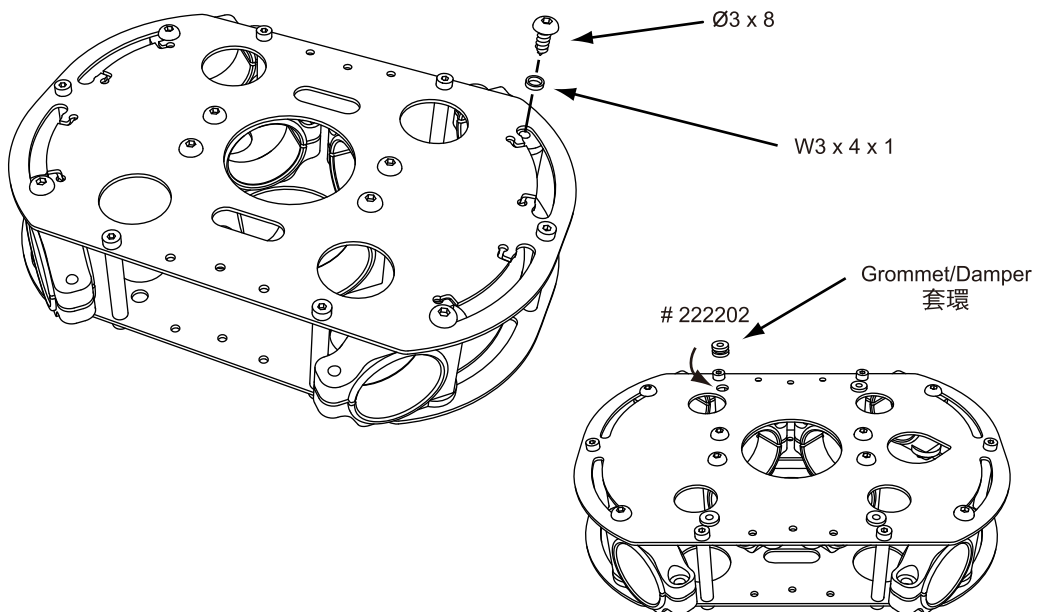
Lock in place the four Outside Boom Holder with (Ø3 x 8) screws (Attention: Outside boom holder screw hole is on top side Frame).
將外部套環如圖的位置鎖上螺絲。(注意：外部套環的螺絲孔在上方)

1



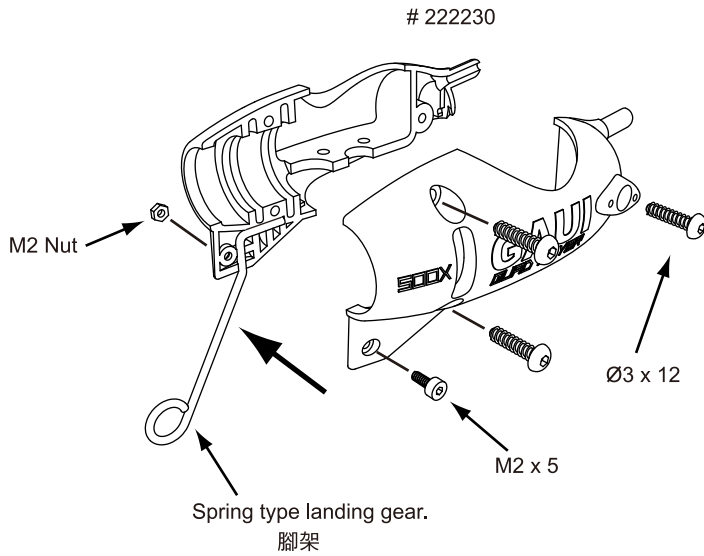
Lock the screws (with washer) in the positions shown in drawing (bottom frame).
將螺絲套入華司小心鎖入機身下方的定位點，最後將套環套入上方的四個孔內。

1

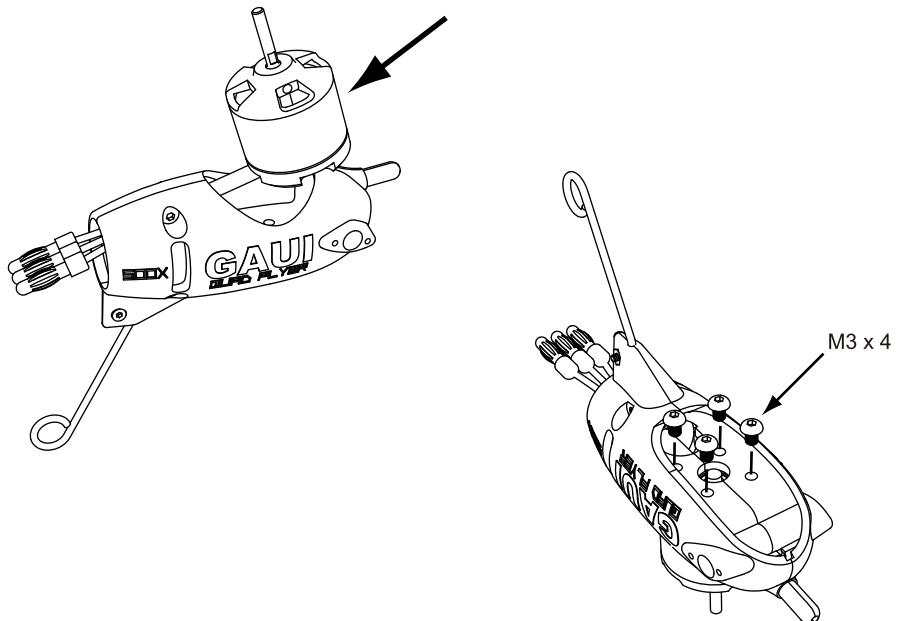


Insert the spring type landing gear into motor base, tighten with screws as drawing indicates.
將腳架置入馬達艙內並鎖上螺絲。

2

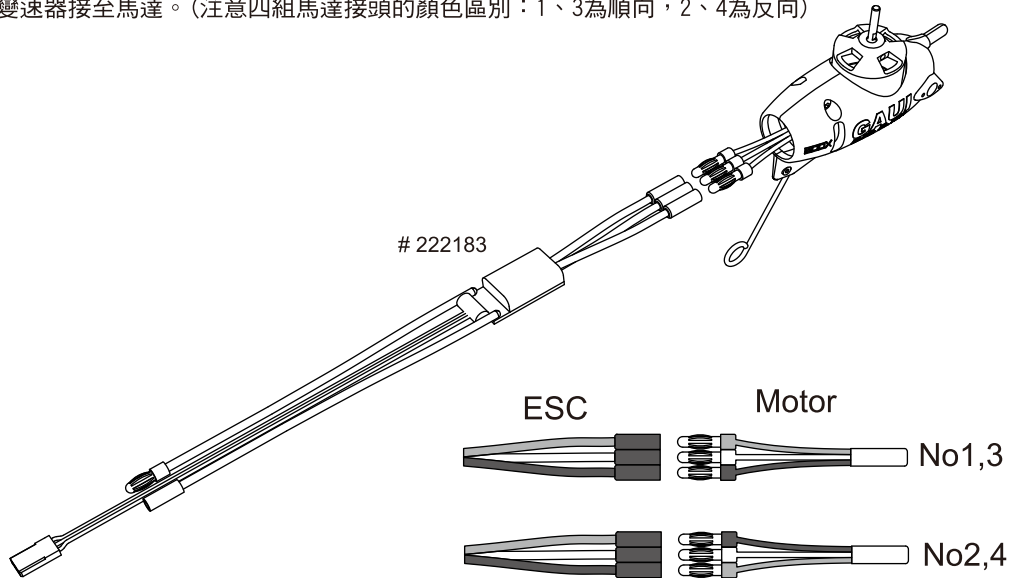


Insert the motor into the motor base and tighten with screws (M3 x 4) as drawing indicates.
將馬達套入馬達艙內並鎖上螺絲。



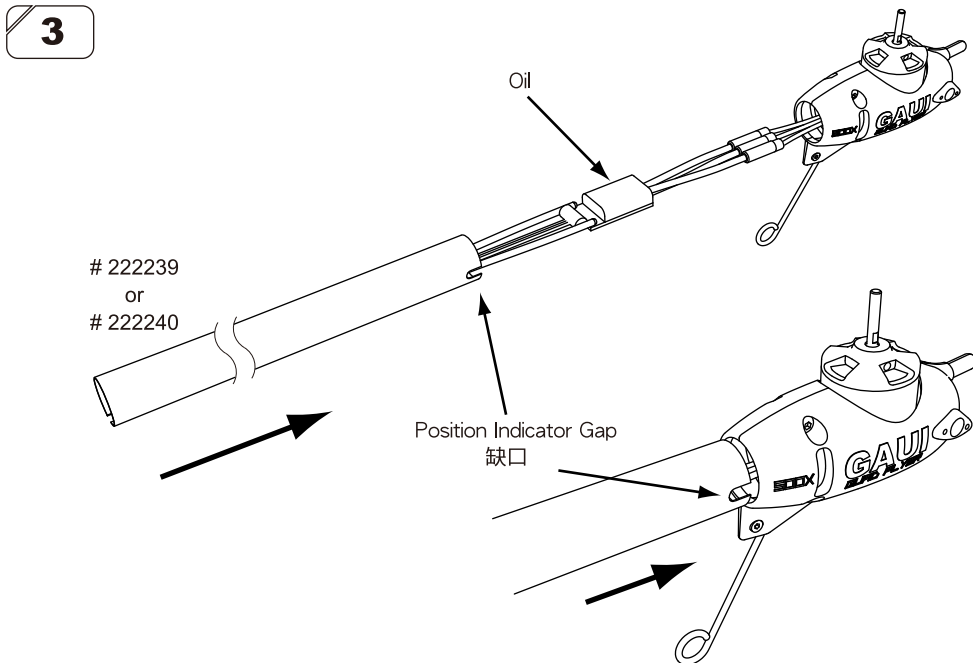
Connect ESC to Motors (Attention on cable connections: Motor + ESC (motor 1&3 spins Clock Wise) connect the same color cables together; Motor + ESC (motor 2&4 spins Counter Clock Wise) red connects to black, black connects to red & the other cable should connect same color cable.

將電子變速器接至馬達。(注意四組馬達接頭的顏色區別：1、3為順向，2、4為反向)



Put a small amount of lubricant oil over the ESC cover and insert into the boom arm (attention on the Position Indicator Gap).

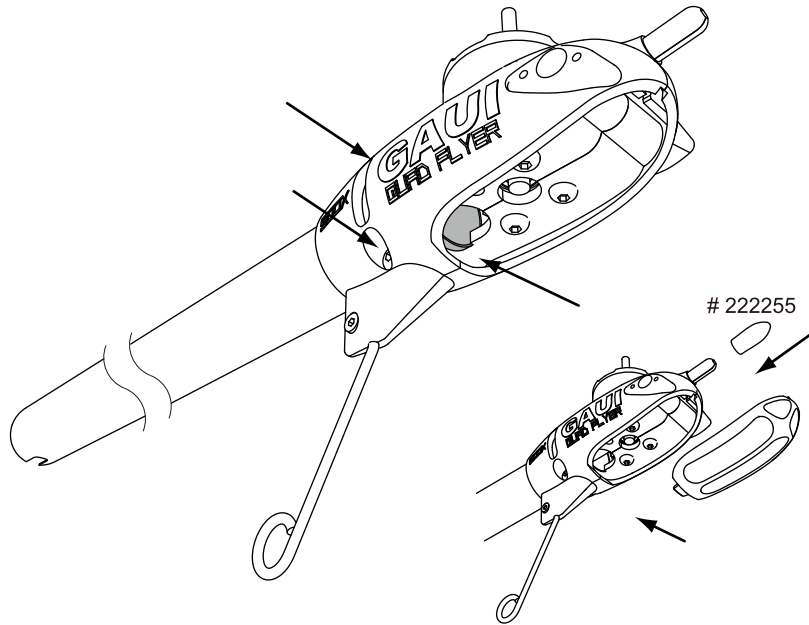
將電子變速器外膜上一點油酯並套入軸管內。(注意軸管缺口位置)



Insert boom into Motor base, attention on Position Indicator Gap, tighten screws and insert VCP Cap & plastic lid cover.

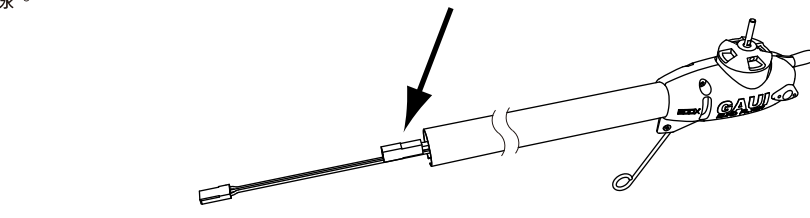
將軸管確實插入馬達艙定位點(軸管必須突出塑膠)，然後鎖緊螺絲並蓋上蓋子及套子。

4



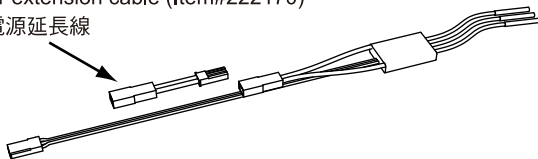
If you are using 330X power system (10A ESC & motor from 330X), note the power cable must extend itself outside of boom arm. If length is not enough you need to add a power extension cable.

若採用330X動力系統(10A ESC)，請注意電源線必須伸出管外，若長度不夠可自行延長或另購電源延長線。



Power extension cable (Item#222170)

電源延長線



ESC

Motor



No1,3



No2,4

Motor 1&3: Connect RED to RED, YELLOW to YELLOW, BLACK to BLACK.

Motor 2&4: Connect RED to BLACK, YELLOW to YELLOW, BLACK to RED.

After connecting Motor/ESC power/signal cables.

Secure cable connections with tapes.

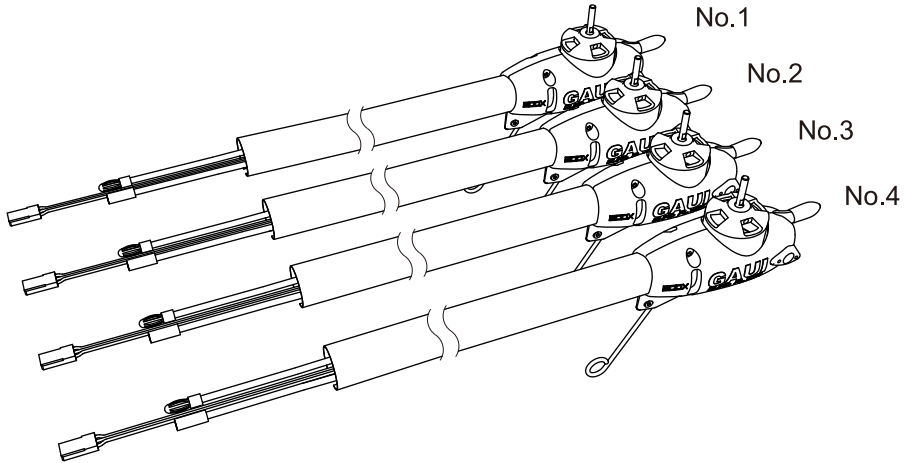
馬達線與ESC接法皆相同，接好後必須以膠帶固定。



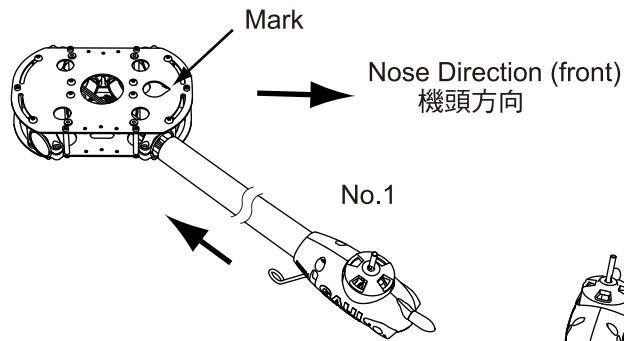
When completing the 4 flight arms (labeling each arm & cables with numbers 1~4 is highly recommended).

* It is important to install the correct flying arms in their own position as the motors spins in different directions (refer to top of page 4 about motor cable connections and spinning direction)

完成四組動力艙後便可逐一組合。

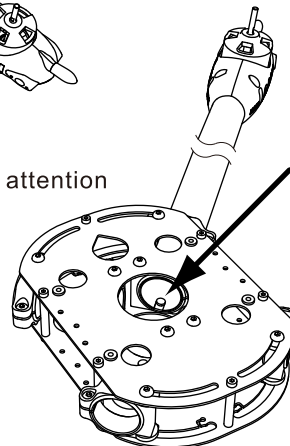


Starts from arm#1, insert into the two lined up rings (attention on Nose direction, front).
首先將一號動力艙由機身外套環插至內套環(注意機身前方位置)。



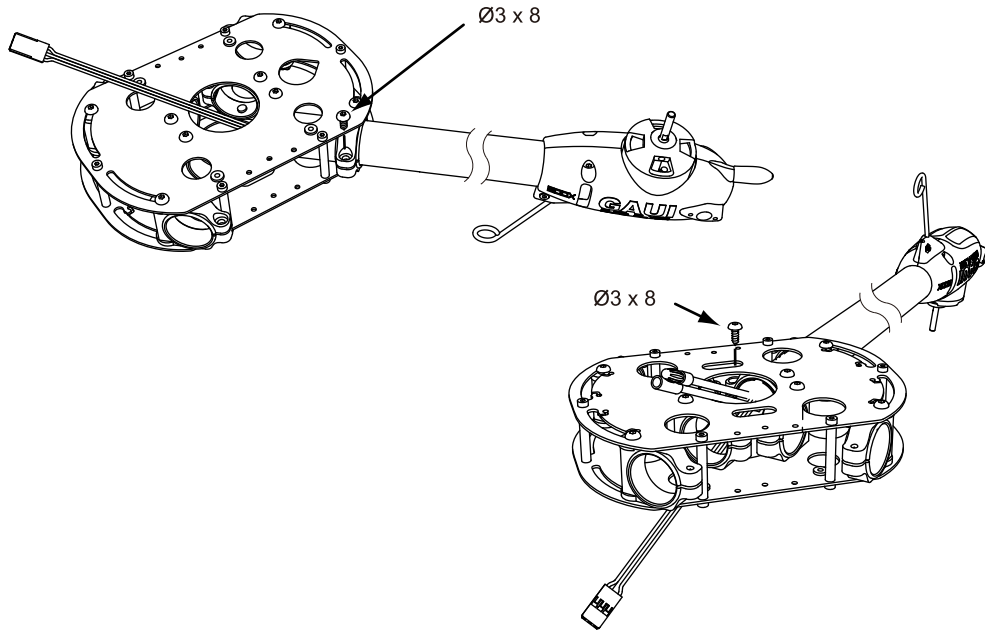
When inserting each arm into the inner ring please pay attention on the Position Indicator Gap (as indicated in drawing).

插至內套環時需注意軸管缺口需在定位點上(如下圖)。



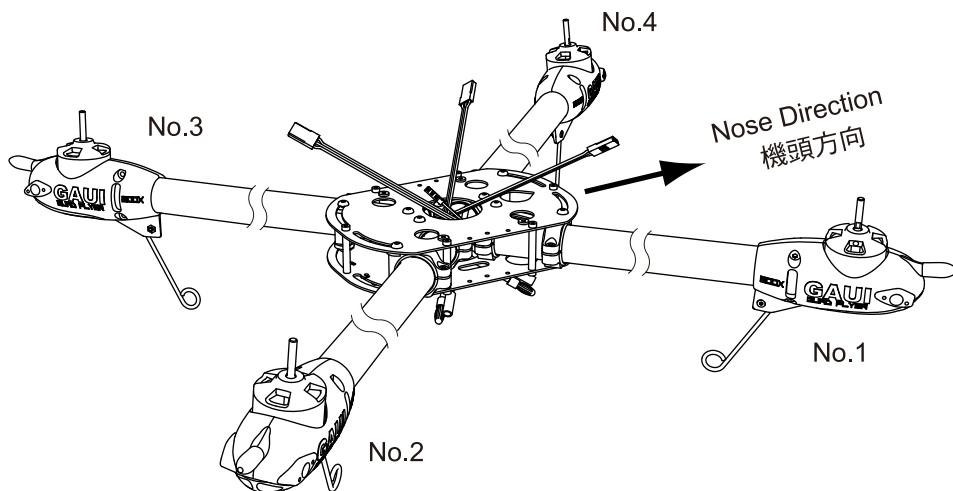
Signal cable should come out from top frame, power cable should come out from bottom frame. Tighten flight arms with $\text{Ø}3 \times 8$ screws.

將訊號線由上方穿出，電源線由下方穿出，並將內外套管鎖上螺絲固定。

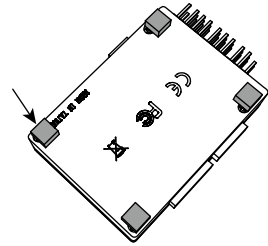
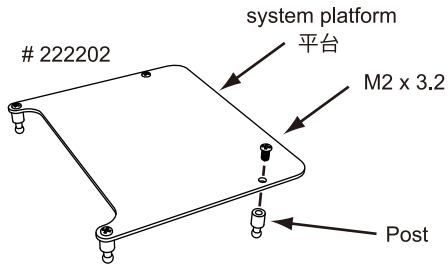


Use same method and complete the other three flight arms.

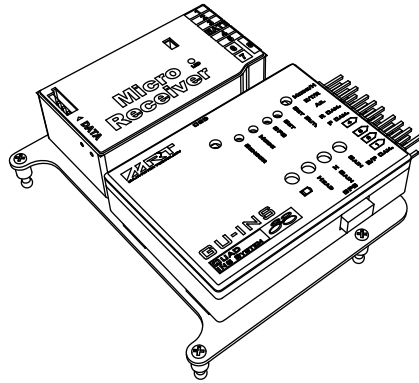
相同方法逐一將四個動力艙組合。



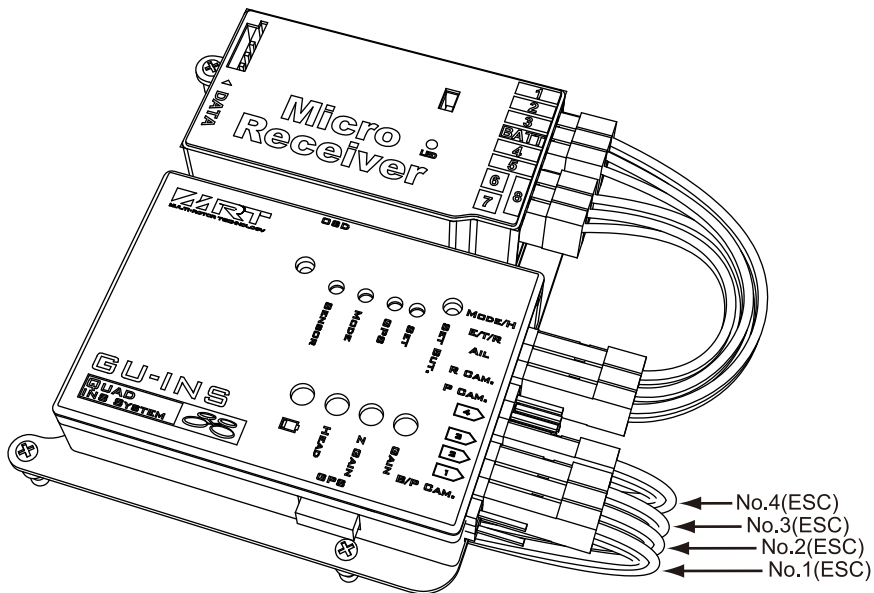
5



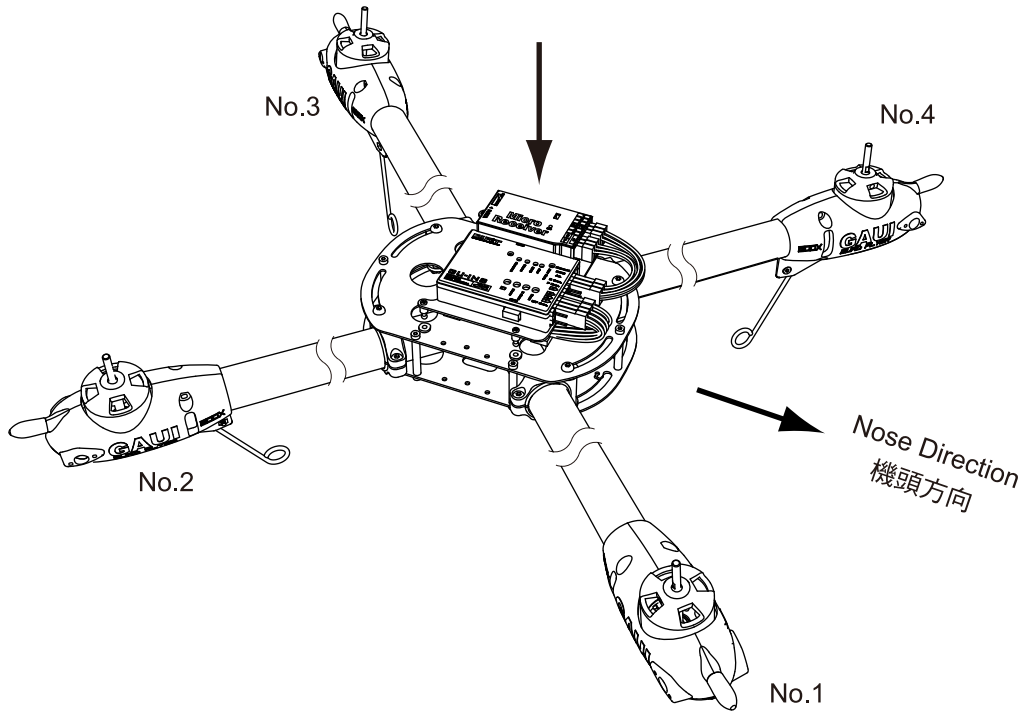
Put the anti-vibration sponges to the four corners of GU-INS (please use the sponges included with GU-INS).
將防震泡棉貼於GU-INS本體的四個角落。



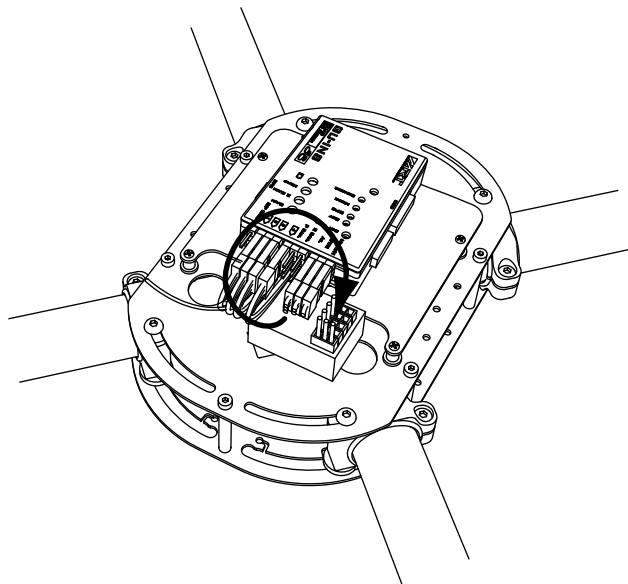
Receiver/GU-INS (multi rotor flight stabilizer system) / ESC cable connections illustration.
GU-INS與接收機及四個動力艙的接法如下。



Insert the System Platform onto the main frame (attention on nose direction).
將平台固定在機身的套環上(注意機頭方向)。

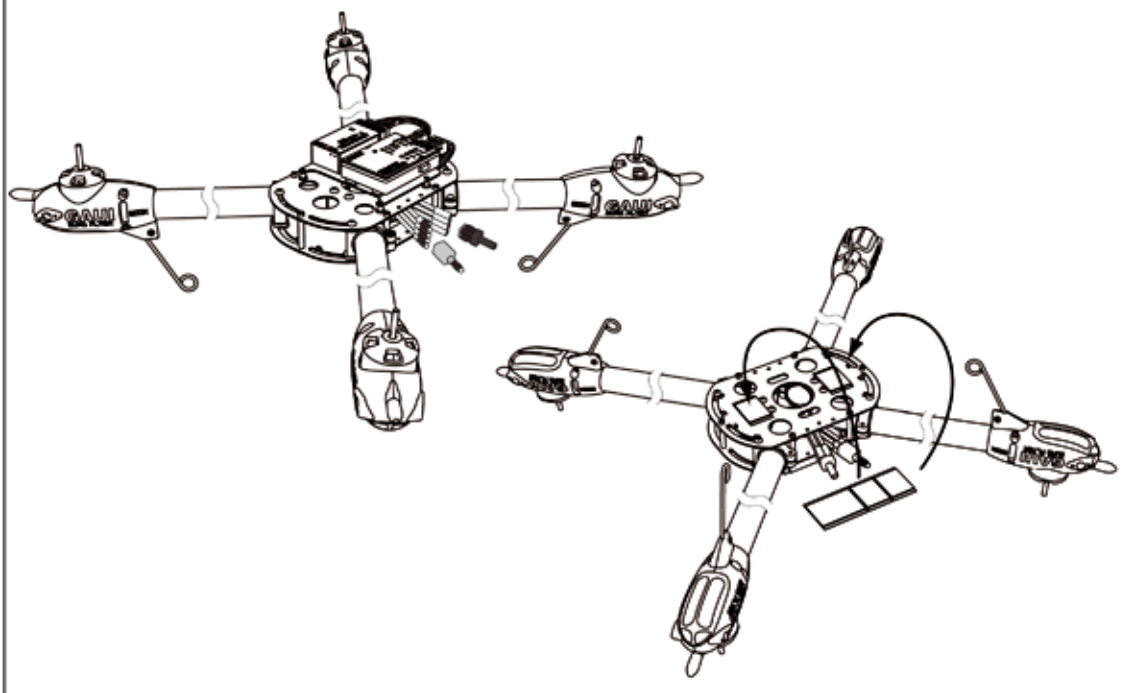


Note: when using a receiver with top cable connection instead of side cable connection. Install the receiver on the main frame (top frame) and not on the platform as the canopy will not have enough space.
若採用上插的接收機時，請將接收機固定於平台下，以免艙罩無法蓋上。



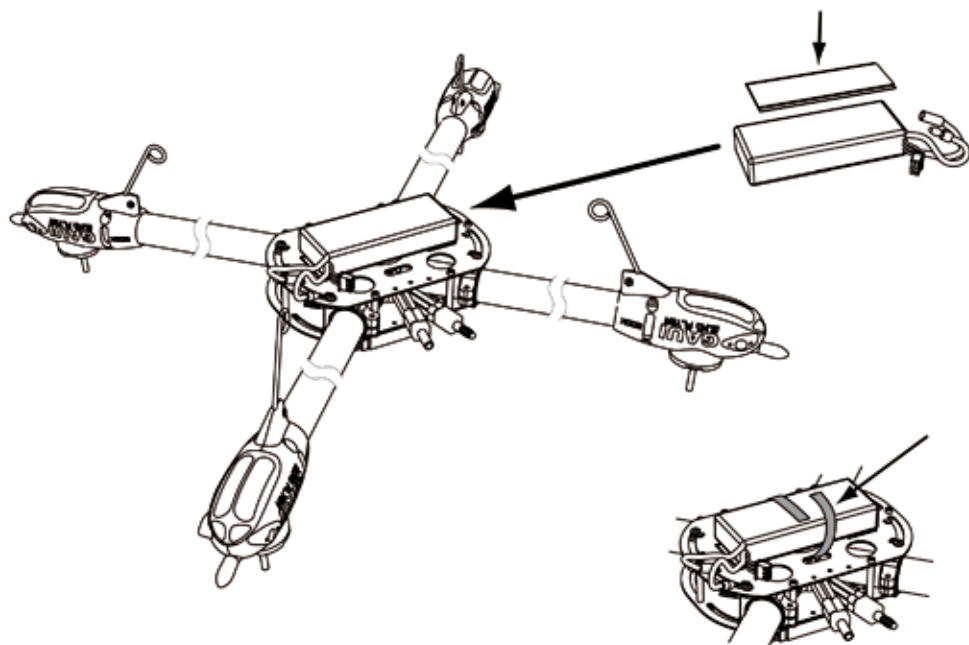
Connect the power cables to the 4-to-1 power connector, the battery connector should show thru the side of the main frame body (as indicated in drawing). Put touch fastener tapes onto the bottom of main frame body for attaching battery.

將電源線由機身側面穿出並接上四合一接頭，同時將魔術氈剪成小段貼於機身下方。



Also put touch fastener on battery pack and affix to bottom of frame. (If the battery is too heavy, you can also use GAUI cable tie with velcro fastener to secure even more).

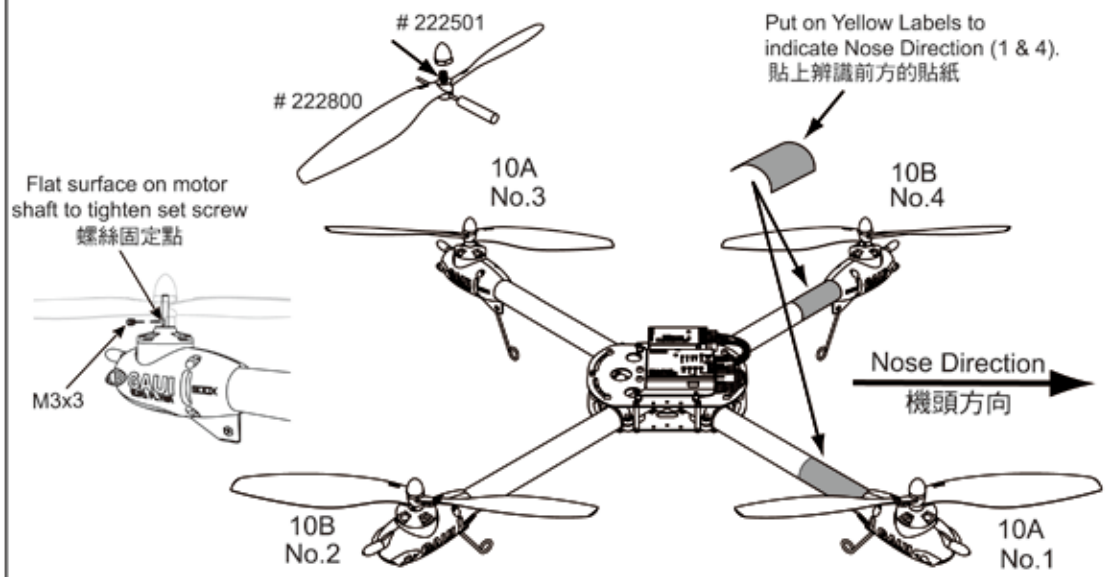
將電池貼上魔術氈後固定於機體下方(若電池太重也可以用束帶固定)。



Use the Spinner (bullet shaped part) to install the propeller on the propeller adaptor (threaded).

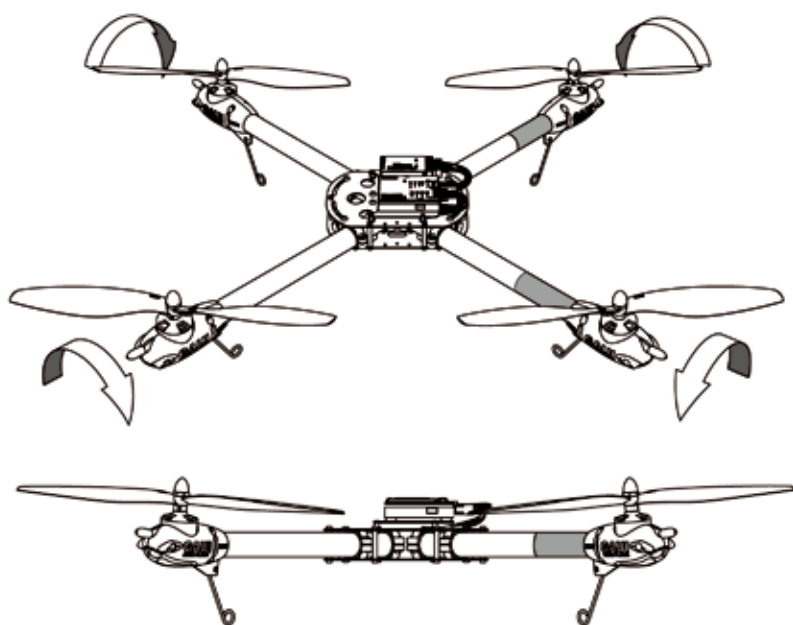
Tighten the propeller set onto the motor shaft (Attention: Motor 1&3 spins counter-clock-wise and use 10A propellers. Motors 2&4 spins clockwise and use 10B propellers). Correct propeller installation is needed for flight.

用機鼻將螺旋槳固定在轉接頭上，並用螺絲將轉接頭鎖在馬達軸心的平面上(注意：1及3為逆時鐘旋轉用10A槳，2及4為順時鐘旋轉用10B槳，不可裝錯)。



The propellers after installation is not totally horizontal, this is normal, the deviation / tilt is about 6 degrees . See drawing below, the motor base and motor after correct installation of the boom arms (position indicator gap).

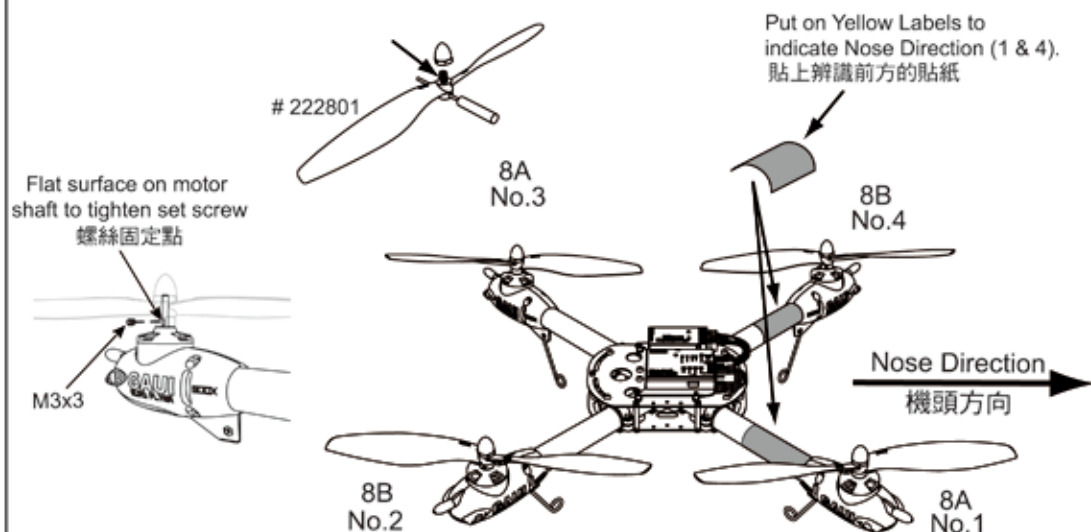
螺旋槳並非垂直向上，它應該呈現6度偏角(如下圖所示)。



Use the Spinner (bullet shaped part) to install the propeller on the propeller adaptor (threaded).

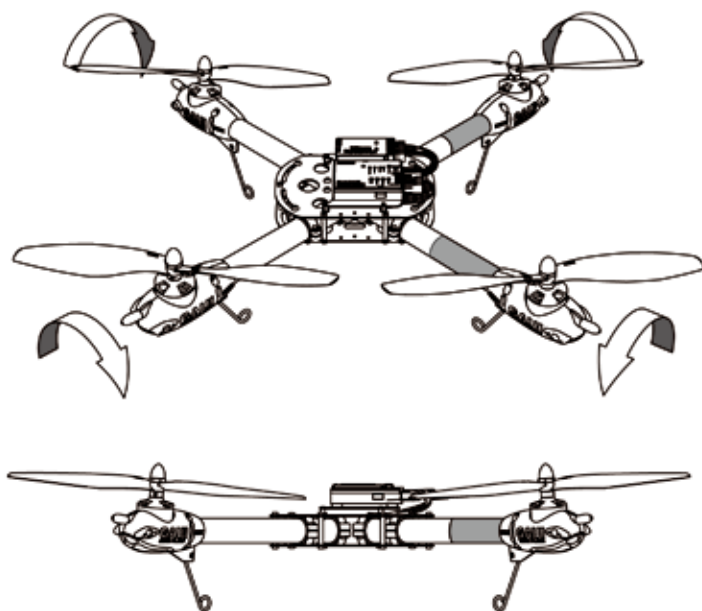
Tighten the propeller set onto the motor shaft (Attention: Motor 1&3 spins counter-clock-wise and use 8A propellers. Motors 2&4 spins clockwise and use 8B propellers). Correct propeller installation is needed for flight.

用機鼻將螺旋槳固定在轉接頭上，並用螺絲將轉接頭鎖在馬達軸心的平面上(注意：1及3為逆時鐘旋轉用8A槳，2及4為順時鐘旋轉用8B槳，不可裝錯。



The propellers after installation is not totally horizontal, this is normal, the deviation / tilt is about 6 degrees . See drawing below, the motor base and motor after correct installation of the boom arms (position indicator gap).

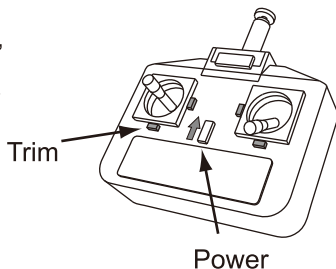
螺旋槳並非垂直向上，它應該呈現6度偏角(如下圖所示)。



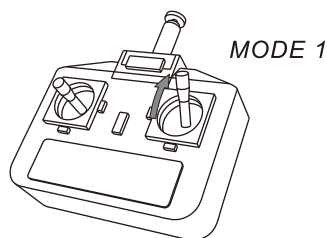
Adjust and unify the starting signal for each ESC before first flight to make sure each motor is run by its ESC with the same output signal. Otherwise under low speed start-up, some motors will turn, some will not.

初次飛行需校正四組ESC訊號的一制性(校正一次即可), 否則會有低速啟動時, 馬達有些轉有些不轉的現象。

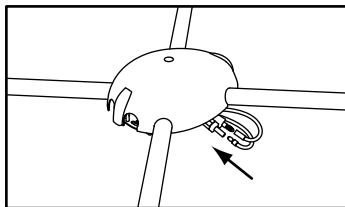
1. Switch on transmitter power, set all trims to neutral.
打開發射機, 先將微調置於中立。



2. Move the throttle stick to the top position (figure indicates the "THROTTLE" control stick for "MODE 1" transmitter)
將油門 (THROTTLE) 桿撥至最大。(圖示為 Mode 1 遙控器)



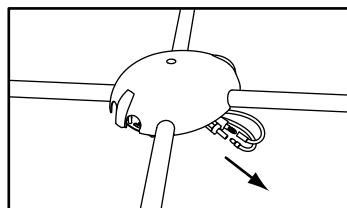
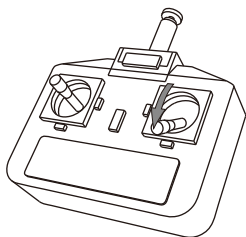
3. Connect the battery to the 350X / 500X.
將350X / 500X的電池接上。



4. After battery is connected to the 500X, the motor will come up with 5 corresponding tones (♪-♪-♪---♪-♪), move the throttle stick to the lowest position, the motor will sound with 3 acknowledge tones(♪-♪---♪), simply disconnect the battery from the 500X, setting is completed (The ESCs are initialized with Factory Default setting for 500X, referring to page 17 for detailed information on ESC setting.)* If the motor come up with 6 corresponding tones after the battery is connected, it means your "Throttle command" is set to reverse, change your "Throttle command" to Normal on your transmitter and re-start "Step 2 to 4" above.

此時你會聽到馬達發出登-登-登---登-登 5個音, 接下來將油門撥桿朝下, 此時你會聽到登-登---登 3個音, 此時將500X的電源關掉, 便已完成指令校正。(其它設定值已出廠設定完成, 詳細內容請參考電子變速器設定說明。)

*若你聽到的聲音一開始是 登-登-登---登-登---登 6個音, 那表示THRO的指令相反, 請改變THRO的正反設定。



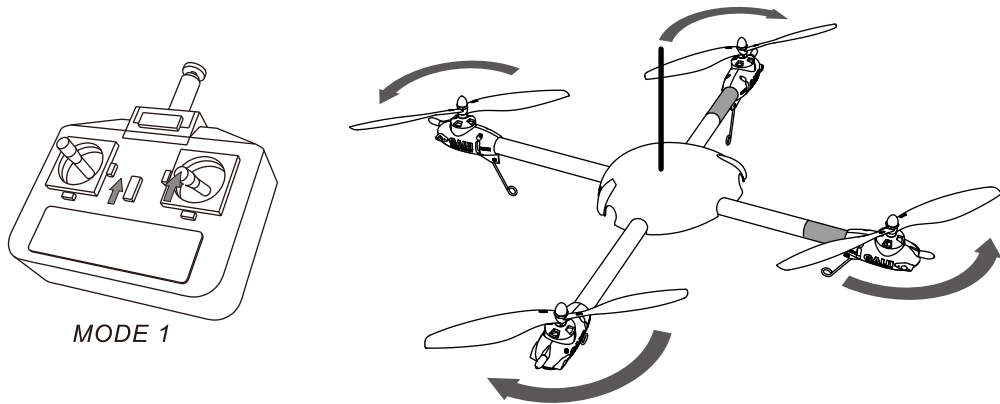
Move the throttle stick to the lowest position and switch on power of transmitter, connect battery to the 500X and do not move/shake it until the motor come up with 6 acknowledging tones (♪-♪-♪-♪-♪-♪), now it is ready for flight.

2S Lipo

先將發射機開關打開(油門THRO置於最低點), 500X的電源接上後不要搖晃機體, 等馬達發出登-登-登---登-登(代表2S電池)---登 6個音後便可開始操作。

Check the operating direction of each motor and propeller on the ground first to make sure the 350X / 500X is able to be controlled correctly by the transmitter. Set the transmitter functions properly if it did not come with correct response (figure shown is the "THOR" control stick of "MODE 1" transmitter).

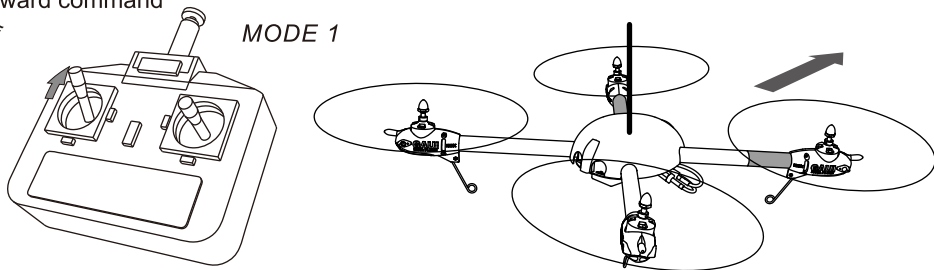
剛開始先不要將350X / 500X離地(在地上滑行), 先測試螺旋槳轉動方向對不對, 再來測試前後, 轉彎及左右方向對不對, 若有方向相反, 請由遙控器做指令反向調整。(圖示為 Mode 1 遙控器)



Move the "ELE" stick a little bit upward to check and make sure the 350X / 500X tilts forward as shown in figure below (figure below indicates the "ELE" control stick of "MODE 1" transmitter).

*Move forward command

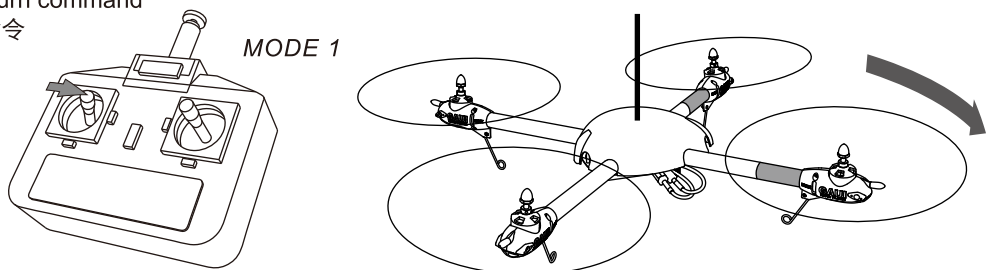
*向前指令



Move the "RUD" stick rightward to check and make sure the 350X / 500X rotates(turn right) as shown in figure below (figure below indicates the "RUD" control stick of "MODE 1" transmitter).

*Right turn command

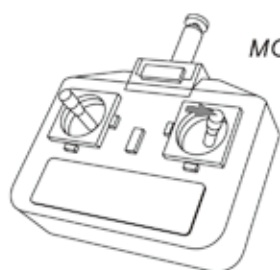
*右轉指令



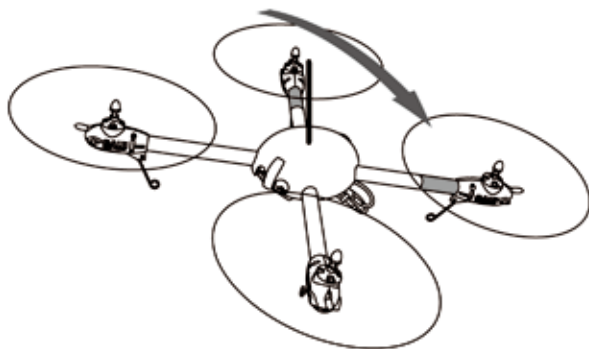
Move the "AIL" stick rightward to check and make sure the 500X tilts right as shown in figure below (figure indicates the "AIL" control stick of "MODE 1" transmitter)

*Lean right command

*右傾指令

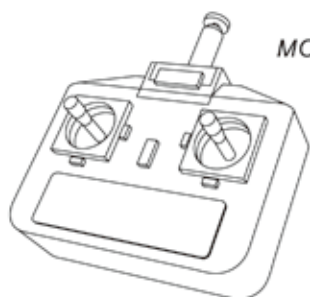


MODE 1

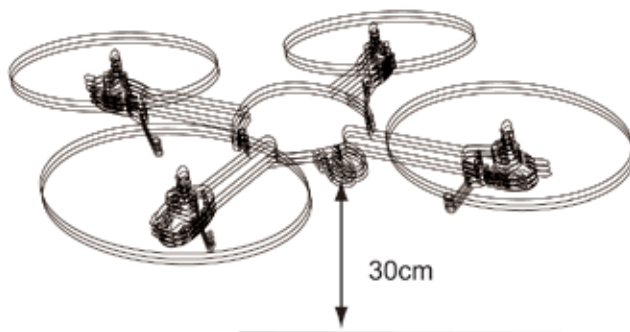


After checking that all movements of the 350X / 500X are controlled correctly by control sticks, move the "THR" stick a little bit upward until the 350X / 500X hovers about 30cm above the ground, if it shakes or wags in hovering, decrease the "GAIN value" until the 350X / 500X hover is stable (refer to page 12 for GAIN value setting on flight stabilizer system.)

指令無誤後, 接下來將油門再往上一些, 讓350X / 500X離地約30公分, 若發現機體有抖動現象時, 請將GAIN值調小到不會晃動為止。(GAIN的調整見系統設定篇)



MODE 1



Program the ESC with your transmitter (4 Steps):

1. Enter program mode
2. Select programmable items
3. Set item's value (Programmable value)
4. Exit program mode

1. Enter program mode

- a). Switch on transmitter, move throttle stick to top, connect the battery pack to ESC
- b). Wait for 2 seconds, the motor should emit special tone like "beep-beep"
- c). Wait for another 5 seconds, special tone like "♪ 56712" should be emitted, which means program mode is entered.


2. Select programmable items:

After entering program mode, you will hear 8 tones in a loop with the following sequence. If you move the throttle stick to bottom within 3 seconds after one kind of tones, this item will be selected.

1	"beep"	brake	(1 short tone)
2	"beep-beep"	battery type	(2 short tone)
3	"beep-beep-beep"	cutoff mode	(3 short tone)
4	"beep-beep-beep-beep"	cutoff threshold	(4 short tone)
5	"beep —"	startup mode	(1 long tone)
6	"beep — beep"	timing	(1 long 1 short)
7	"beep — beep-beep"	set all to default	(1 long 2 short)
8	"beep — beep —"	exit	(2 long tone)

Note: 1 long "beep——" = 5 short "beep—"

3. Set item value (Programmable value):

You will hear several tones in loop. Set the value matching to a tone by moving throttle stick to top when you hear the tone, then a special tone "♪ 1515" emits, means the value is set and saved. (Keeping the throttle stick at top, you will go back to step 2 and you can select other items; Moving the stick to bottom within 2 seconds will exit program mode directly)

Tones	"beep—" 1 short tone	"beep-beep—" 2 short tones	"beep-beep-beep—" 3 short tones
Brake	Off	On	
Battery type	Li-ion / Li-poly	NiMH / NiCd	
Cutoff mode	Soft-Cut	Cut-Off	
Cutoff threshold	Low	Medium	High
Start mode	Normal	Soft	Super soft
Timing	Low	Medium	High

4. Exit program mode:
There are 2 ways to exit program mode:
1. In step 3, after special tone "♪ 1515", please move throttle stick to the bottom position within 2 seconds.
2. In step 2, after tone "beep — beep —" (ie. The item #8), move throttle stick to bottom within 3 seconds.

使用遙控器進行參數設定的說明

使用遙控器油門搖杆設定參數分為四個步驟：

- 一. 進入程式設定
- 二. 選擇設定項
- 三. 選擇設定項下的參數值
- 四. 退出

一. 進入程式設定模式:

1. 開啟遙控器，將油門打到最高，電變接上電池。
2. 等待2秒，馬達鳴叫(嗶-嗶-)提示音。
3. 再等待5秒，馬達鳴叫(♪ 56712)特殊提示音，表示已經進入設定模式。


二. 選擇設定項:

進入程式設定模式後，會聽到8組鳴音，按如下順序循環鳴叫，在鳴叫某組提示音後，3秒內將油門打到最低，則進入該設定項。

1	嗶	煞車	(1短音)
2	嗶-嗶-	電池類型	(2短音)
3	嗶-嗶-嗶-	低壓保護方式	(3短音)
4	嗶-嗶-嗶-嗶-	低壓保護閾值	(4短音)
5	嗶——	啟動模式	(1長音)
6	嗶——嗶-	進角	(1長1短)
7	嗶——嗶-嗶-	恢復出廠預設值	(1長2短)
8	嗶——嗶——	退出	(2長)

注：一長音“嗶——”相當於5聲短音“嗶-”，所以在第二步(選擇設定項目)中，一長-短(嗶——嗶-)表示第6選項。

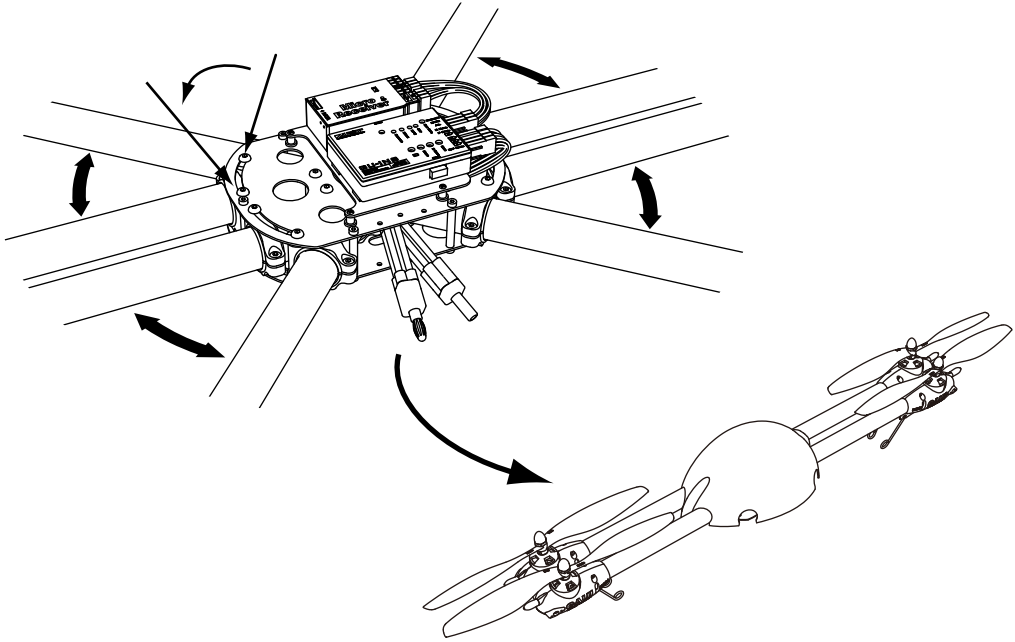
三. 選擇參數值:

馬達會循環鳴叫，在鳴叫某組提示音後將油門搖杆打到最高點，則選擇該提示音所對應的設定值，接著鳴叫特殊提示音(♪ 1515)表示該參數值已被保存。
(此時如果不想再設定其他選項，則在2秒內將油門搖杆打到最低，即可快速退出程式設定模式；如果還要設定其他選項，則繼續等待，退回第二步驟，再選擇其他設定選項)

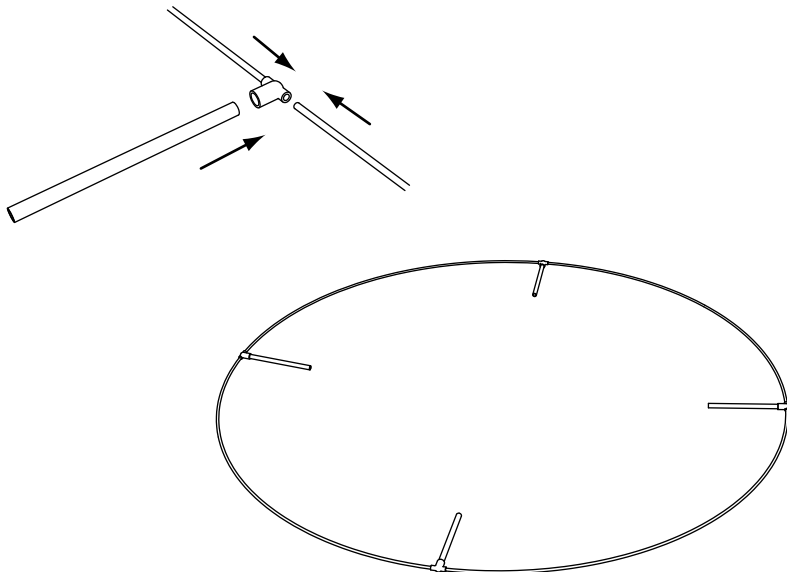
提示音	"嗶—" 1短音	"嗶- 嗶-" 2短音	"嗶- 嗶- 嗶-" 3短音
1. 煞車	無煞車	有煞車	
2. 電池類型	鋰電池	鎳鎘/鎳氫電池	
3. 低壓保護方式	逐漸降低功率	立即關閉功率	
4. 低壓保護閾值	低	中	高
5. 啟動模式	普通啟動	柔和啟動	超柔和啟動
6. 進角	低	中	高

四. 退出設定:
有如下兩種方式退出設定。
1. 在第三步驟，選擇設定值時，鳴叫特殊提示音(♪ 1515)後，2秒內將油門打到最低點，則退出設定。
2. 在第二步驟，選擇設定選項時，當馬達鳴叫出代表第8設定選項的2長的鳴音後，3秒內將油門打到最低點，則退出設定。

Un-tighten the four screws to move to flight or storage positions.
Remember to Re-tighten the screws when the positions are set.
將上方四個螺絲放鬆後即可收起軸管(不管張開或收起都應該再將螺絲鎖上)。

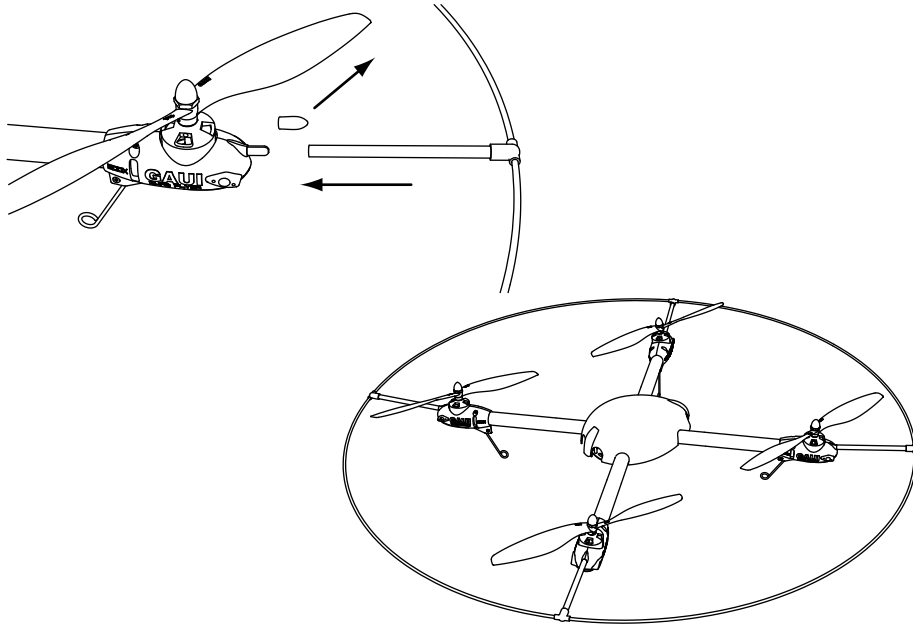


Use the aluminum tubes, plastic connectors and 3mm glass fiber stick to form the protective frame, refer to drawing below (Item#222241).
將3mm玻纖桿及鋁桿用塑膠件結合，並圍成一個外框。



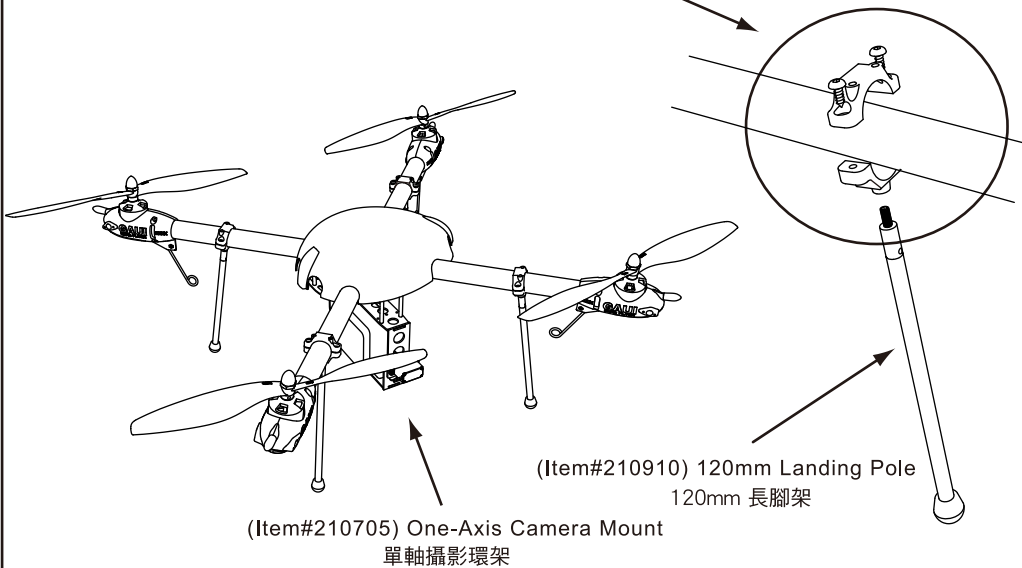
(Item#222241)

Remove the VCP cap and insert the aluminum tubes into its base to complete the quad flyer's protective ring.
將套子取下並插入鋁桿即可完成。



(Item#222231) 管夾 Boom anchor (for landing pole)

管夾



(Item#210910) 120mm Landing Pole
120mm 長腳架

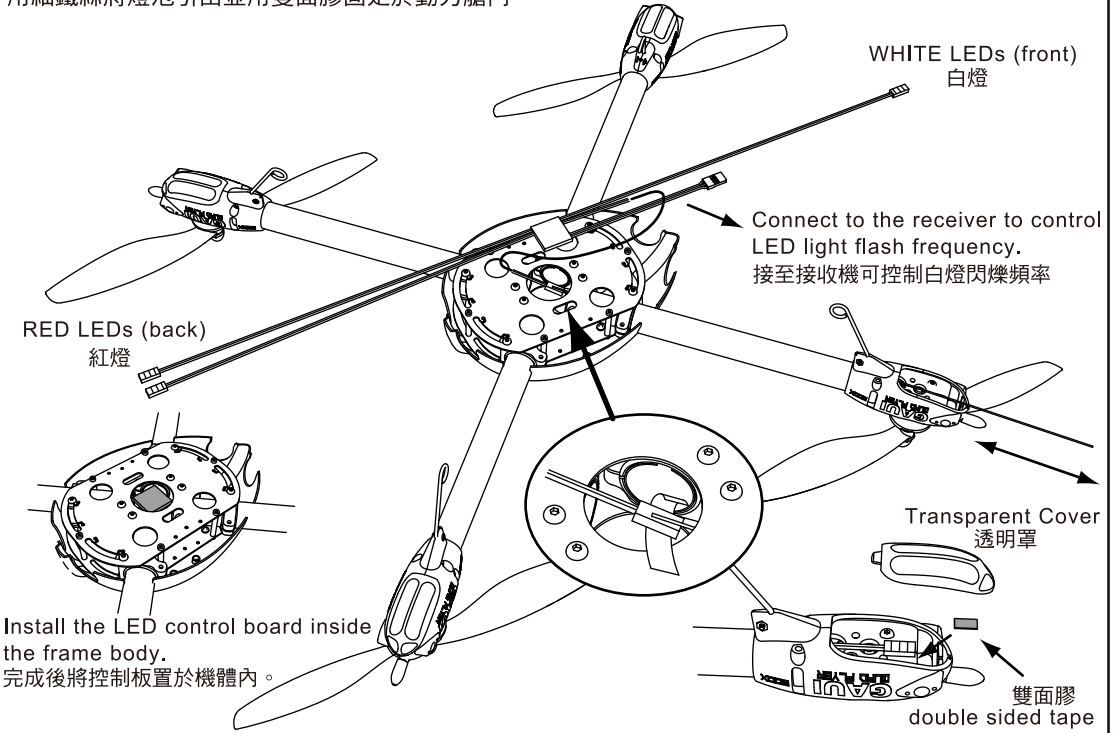
(Item#210705) One-Axis Camera Mount
單軸攝影環架

*500X: CRANE II or GoPro size camera gimbals

*350X: One-Axis / Two-Axis

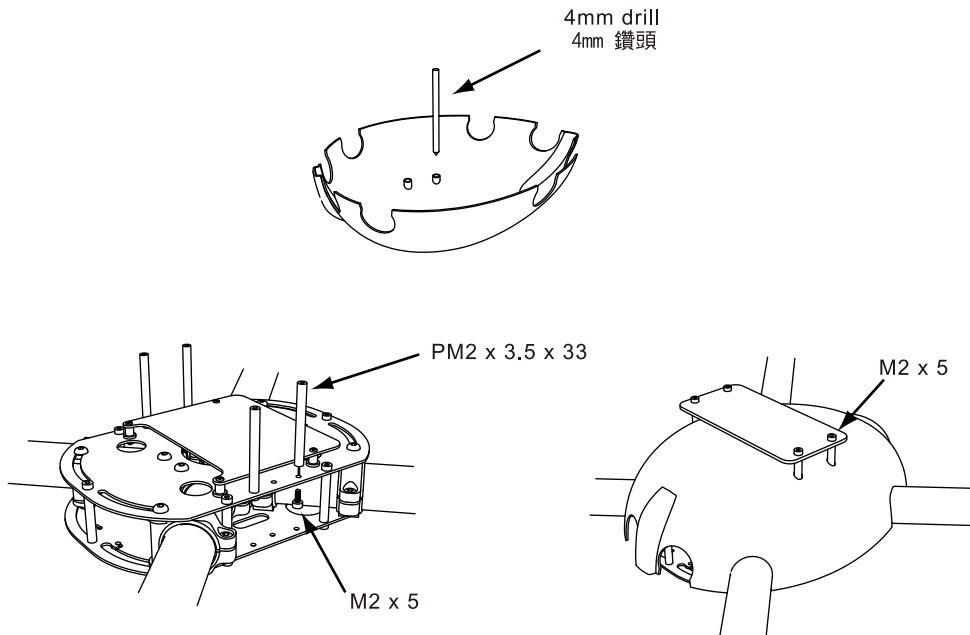
Use metal wires to lead the LED cable wires thru the flight arms (boom) and affix with double sided tape (Item#222180).

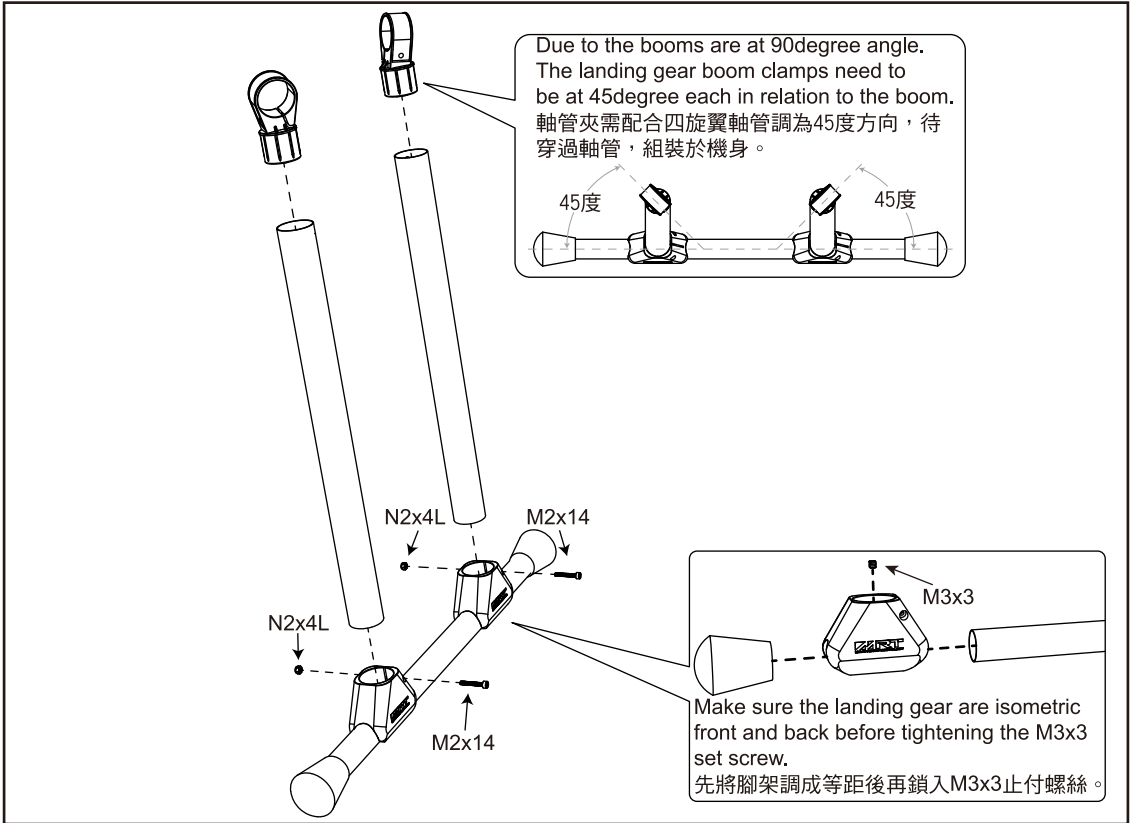
用細鐵絲將燈泡引出並用雙面膠固定於動力艙內。



Drill four 4mm holes into the canopy to install platform (Item#222202).

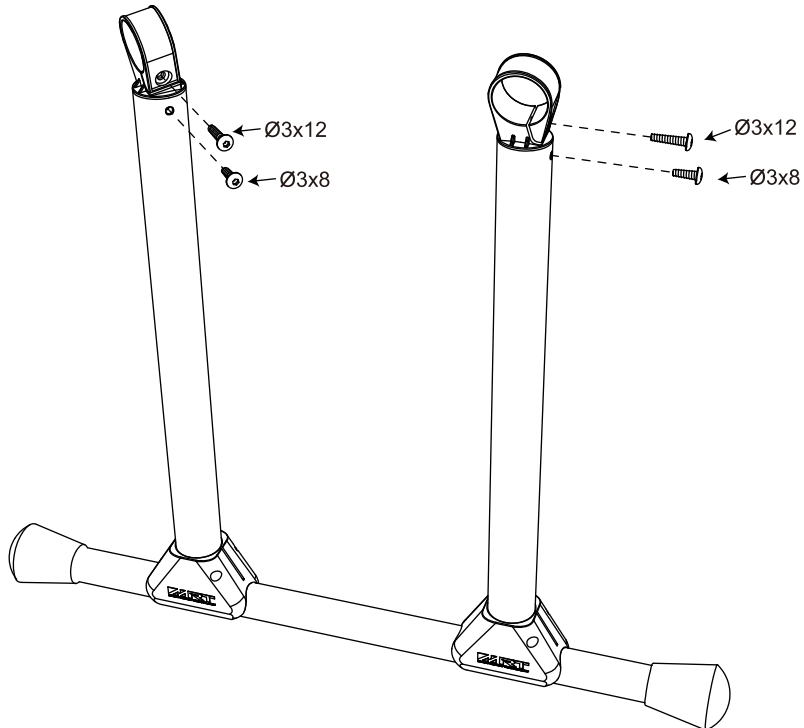
組合鉛柱，並用4mm鑽頭將艙罩鑽出四個孔後置入在鎖上平台。





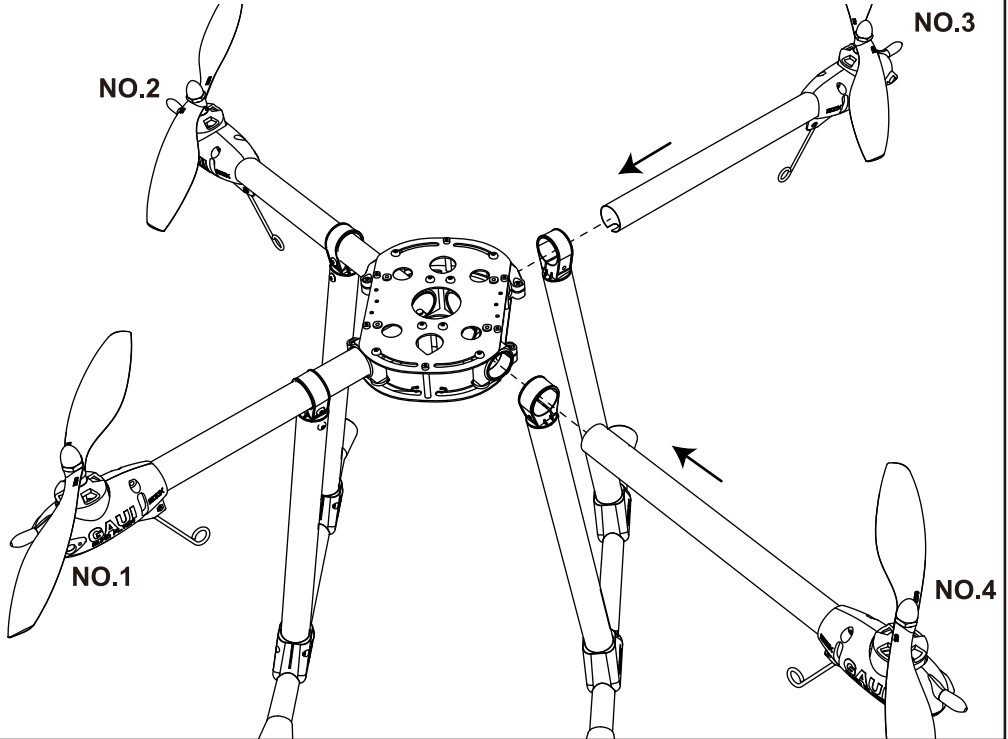
Install the boom clam in position, tighten only $\varnothing 3 \times 8$ screw. Install and tighten $\varnothing 3 \times 12$ screw after the clamp is installed on the boom arm.

軸管夾壓至定位，鎖入 $\varnothing 3 \times 8$ 螺絲，待P.21軸管穿過管夾後調於適當的位置鎖緊 $\varnothing 3 \times 12$ 螺絲。

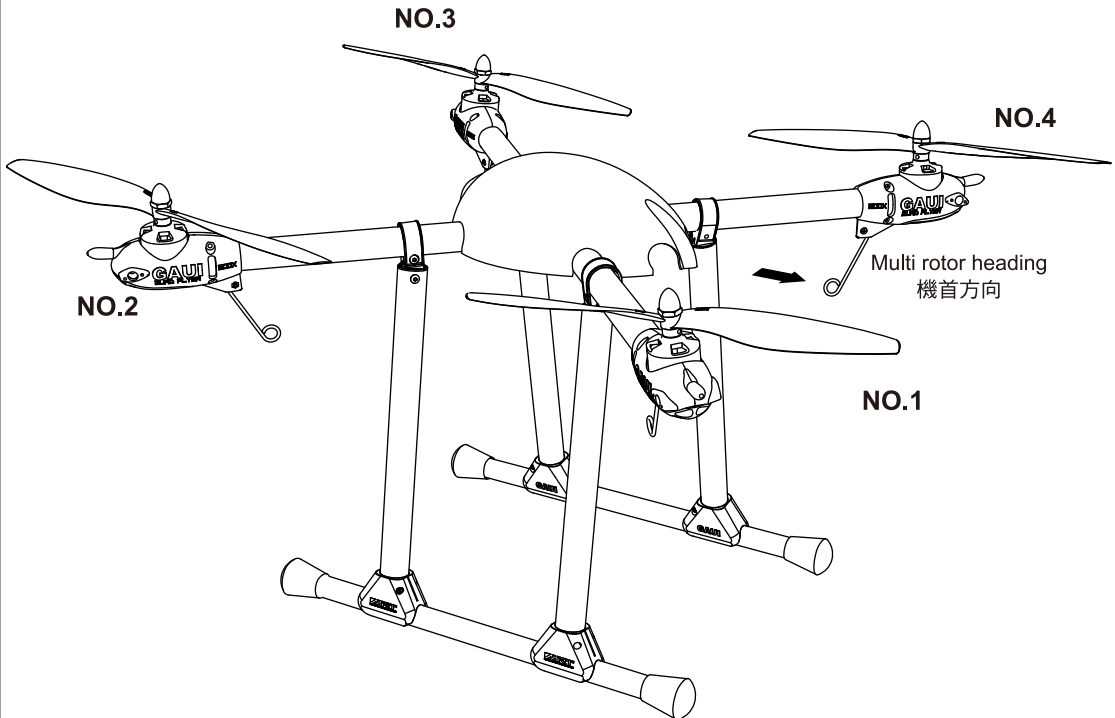


Lead the boom arms thru the landing gear boom clamp, then tighten the $\varnothing 3 \times 12$ screw (please pay attention to the multi-rotor heading).

將軸管穿過軸管夾至定位，再鎖緊P.20 $\varnothing 3 \times 12$ 螺絲。(請注意機首方向)



Landing gear schematic
腳架組裝完成圖。



Item No.	中文品名	Description
210501	螺旋槳機鼻組(內徑3mm)	Adaptor and Spinner Set(For 3mm shaft)
210801	八吋正逆槳	8 in. Props.(8A and 8B)
222170	電源延長線	Power extension cable
222175	四合一電源接頭	4-in-1 Power Connector
222180	LED燈具	LED Light Set(2 White LED,2 Red LED,4 transparent covers)
222183	(GUEC GE-183)電子變速器18A	(GUEC GE-183) 18A (for BL Motor)
222200	玻纖機身	Central Frames
222202	控制平台	System platform
222203	酬載架	Payload Mount Set
222229	艙罩	Windshield Set
222230	動力艙	Motor Mounts
222231	管夾	Boom anchor(for landing poles)
222232	內外套環	Inside & Outside Boom Holder
222240	500X 軸管	500X Boom
222241	防護框	Protection Frame (for 500X)
222255	套管x4	VCP Cap x 4
222411	GUEC GM-412無刷馬達(960KV)	GUEC GM-412 Brushless Motor (960KV)
222412	GUEC GM-412S無刷馬達(960KV)	GUEC GM-412S Brushless Motor (960KV)
222500	鋁柱包(PM2x3.5x22)	Aluminum Posts(PM2x3.5x22)
222800	十吋正逆槳	10 in. Props.(10A and 10B)
225106	MRT 貼紙	MRT Decal
225115	馬達艙固定片	Motor mount cover
225117	350X 軸管	350X Boom arm

QUAD FLYER

350X

&

500X

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